

# YK800XG

Standard type: Medium type

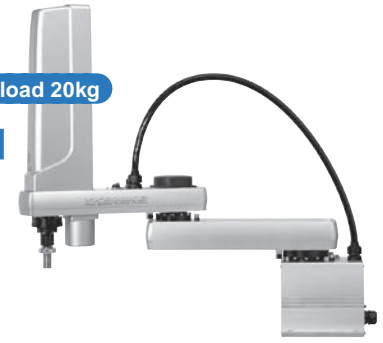
● Arm length 800mm

● Maximum payload 20kg

## Ordering method

YK800XG			RCX240		R3			BB
<b>Model</b>	<b>Z axis stroke</b>	<b>Cable length</b>	<b>Controller</b>	<b>Usable for CE</b>	<b>Regenerative unit</b>	<b>Expansion I/O</b> <small>Note 1</small>	<b>Network option</b>	<b>Battery</b>
	200: 200mm 400: 400mm	SL: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	R3: RGU-3	N, P: Standard I/O 16ch N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link	BB: 4 pcs

Note 1. Use N to N4 when NPN is selected on the I/O board, and P to P4 when PNP is selected.  
Note 2. Available only for the master.



## Specifications

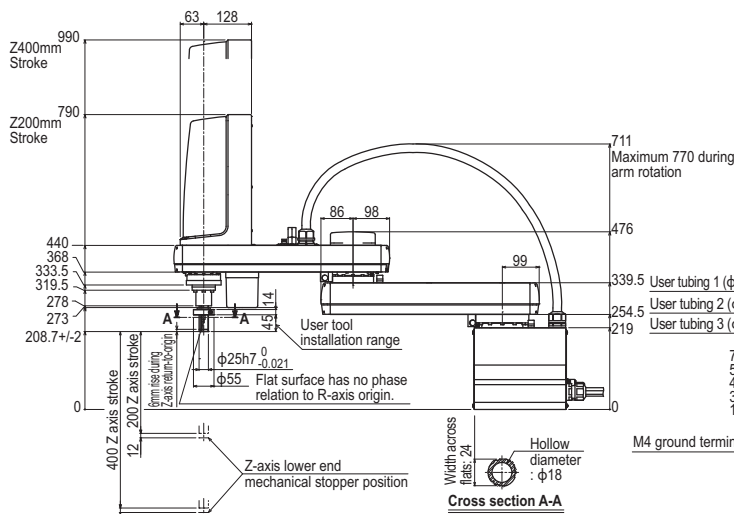
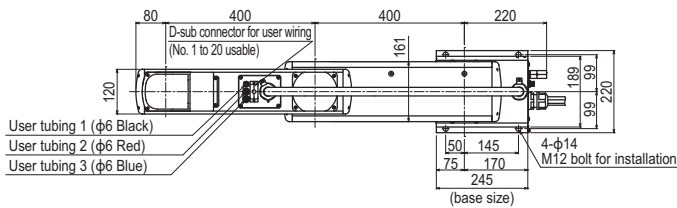
		X-axis	Y-axis	Z-axis		R-axis
Axis specifications	Arm length (mm)	400	400	200	400	-
	Rotation angle (°)	+/-130	+/-150	-	-	+/-360
AC servo motor output (W)		750	400	400	200	
Deceleration mechanism	Speed reducer	Harmonic drive	Harmonic drive	Ball screw	Harmonic drive	
	Transmission method	Motor to speed reducer	Direct-coupled			
	Speed reducer to output	Direct-coupled				
Repeatability <small>Note 1</small> (XYZ: mm) (R: °)		+/-0.02		+/-0.01		+/-0.004
Maximum speed (XYZ: m/sec) (R: °/sec)		9.2		2.3	1.7	920
Maximum payload (kg)		20				
Standard cycle time: with 2kg payload <small>Note 2</small> (sec)		0.48				
R-axis tolerable moment of inertia <small>Note 3</small> (kgm <sup>2</sup> )		1.0				
User wiring (sq x wires)		0.2 x 20				
User tubing (Outer diameter)		φ6 x 3				
Travel limit		1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length (m)		Standard: 3.5 Option: 5,10				
Weight (kg) (Excluding robot cable)		Z axis200mm: 52 Z axis400mm: 54				

Note 1. This is the value at a constant ambient temperature. (X,Y axes)  
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.  
Note 3. There are limits to acceleration coefficient settings.  
Note. Please consult YAMAHHA when connecting other tubes and cables to the self-supporting machine harness.

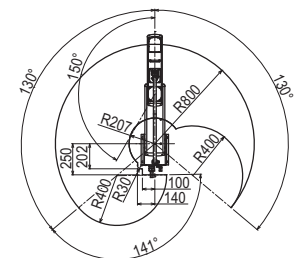
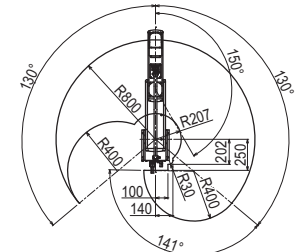
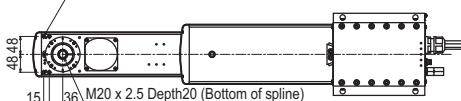
## Controller

Controller	Power capacity (VA)	Operation method
RCX240-R3	2500	Programming / I/O point trace (BCD) / Remote command / Operation using RS-232C communication

## YK800XG



4-M4 x 0.7 through-hole for tool attachment  
Four M4 x 10L binding screws are supplied.  
Do not screw the screws in deeper than 10mm from bottom surface of arm.



X-axis mechanical stopper position: 132°  
Y-axis mechanical stopper position: 152°

